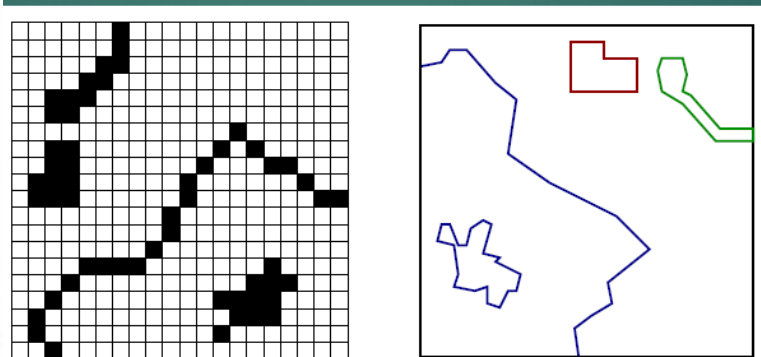
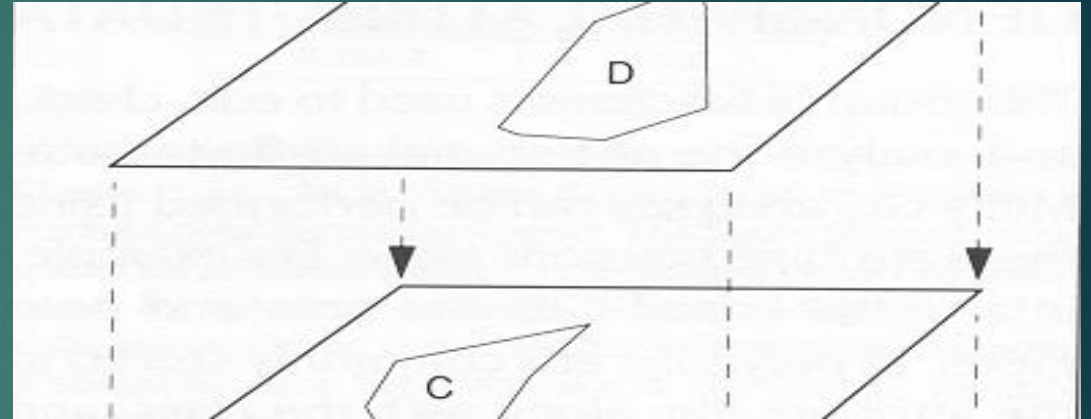
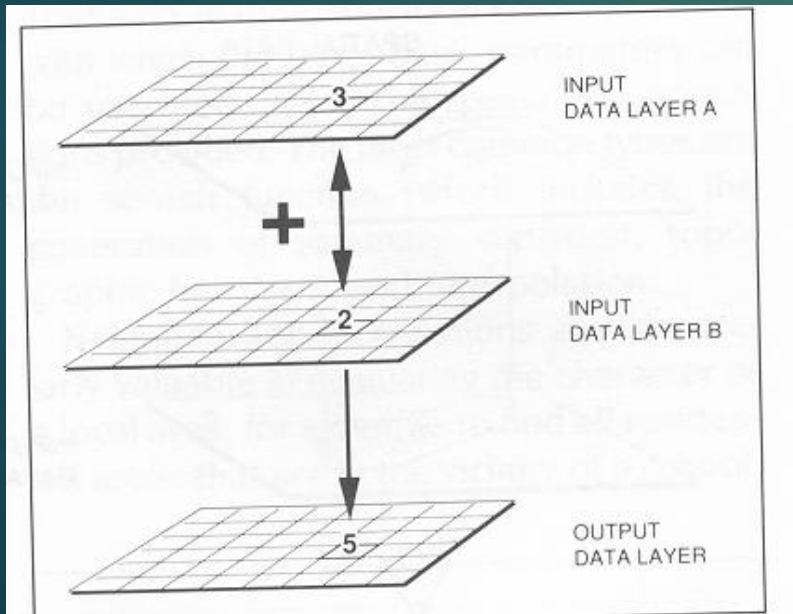


Raster representation

Vector x raster model

Raster x data sample vector
model



Raster representation of spatial models

field shapes

3

Territory divided into **partial mosaic areas** (tessellation , tessera = mosaic cube)

cells do not actually exist - this is a model of the territory, i.e. a way of its representation

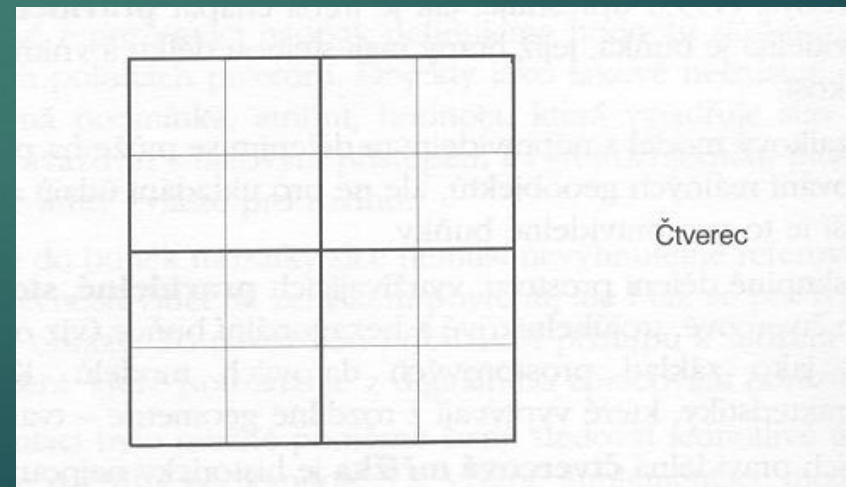
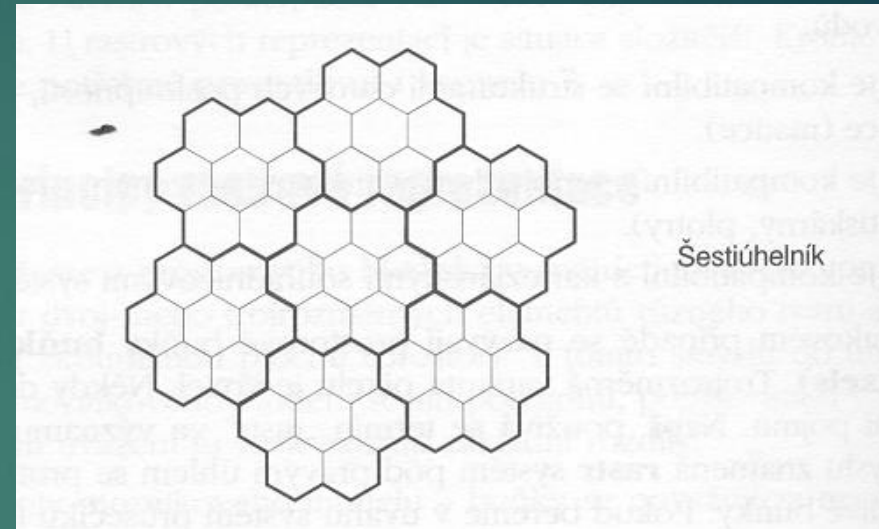
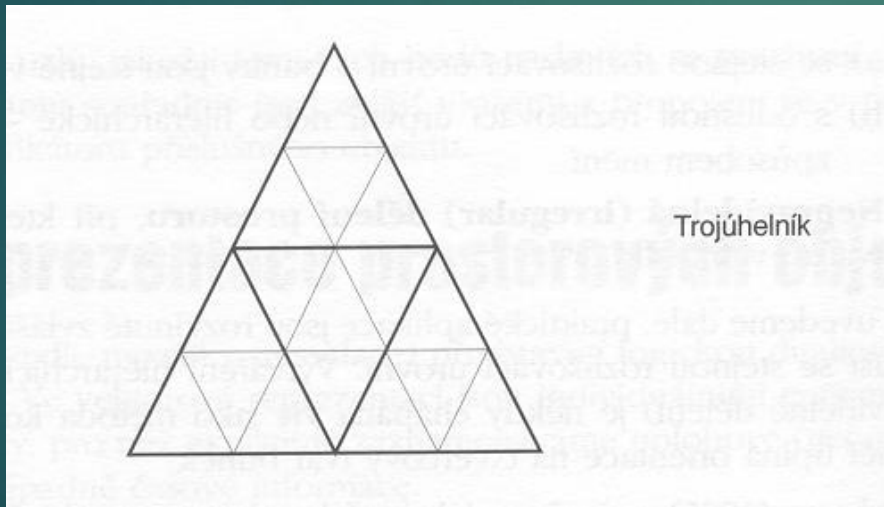
cells = basic areas of the divided space

▶ **Types of division into sub-areas:**

- ▶ **regular**
- ▶ **irregular**

Raster representation of spatial models field shapes

1. Regular division



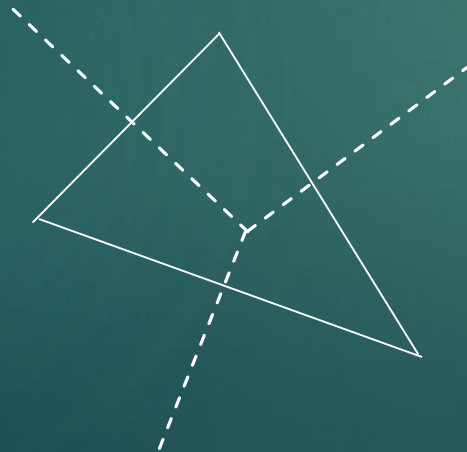
Raster representation of spatial models field shapes

2 . Irregular division - triangles

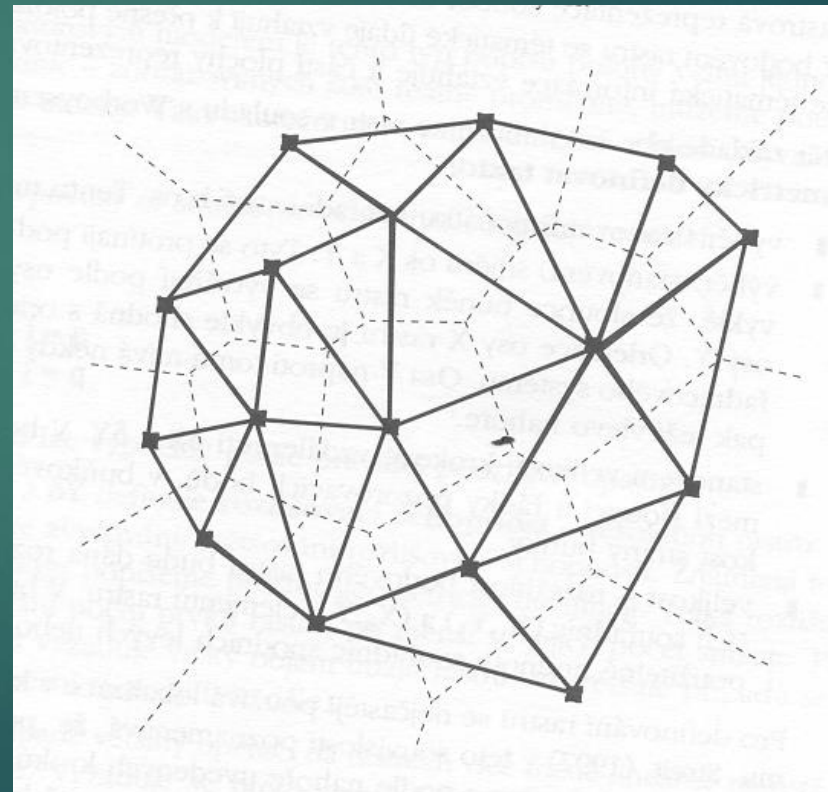
Triangles are created from measured points



Polygons can be created from triangles:



From the lines that are the axes of the sides of the triangles



Raster representation of spatial models

field shapes

6

Delaunay triangles – data at irregularly placed points

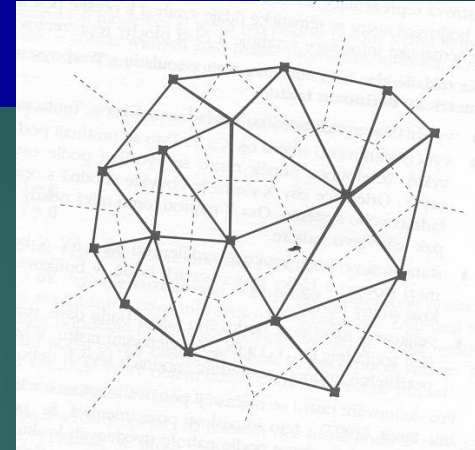
They are such triads that no other point from the data set falls into the circumscribed circle

Voronoi diagram = Thiessen polygons (= Dirichlet tessellation) =

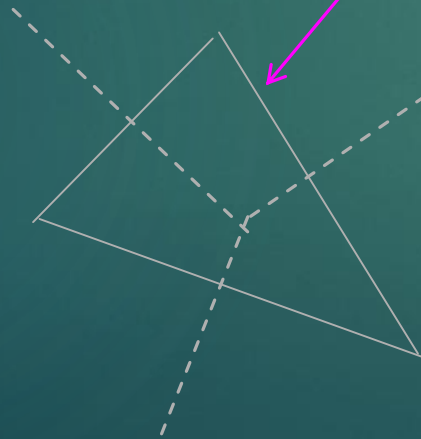
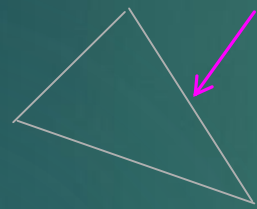
- ▶ the vertices are the centers of the circles described by the Delaunay triangles ,
 - ▶ the edges are perpendicular to the edges Del . triangle . at the centers of these edges
-
- ▶ These objects are **dual to each other**

Raster representation of spatial models field shapes

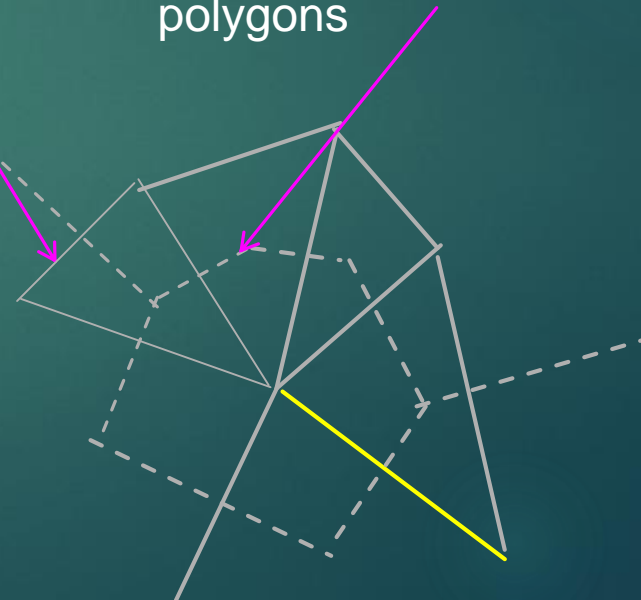
2 . Irregular divisions are not typically raster data



The Delauney's triangles
Their creation see ch.
Digital terrain models



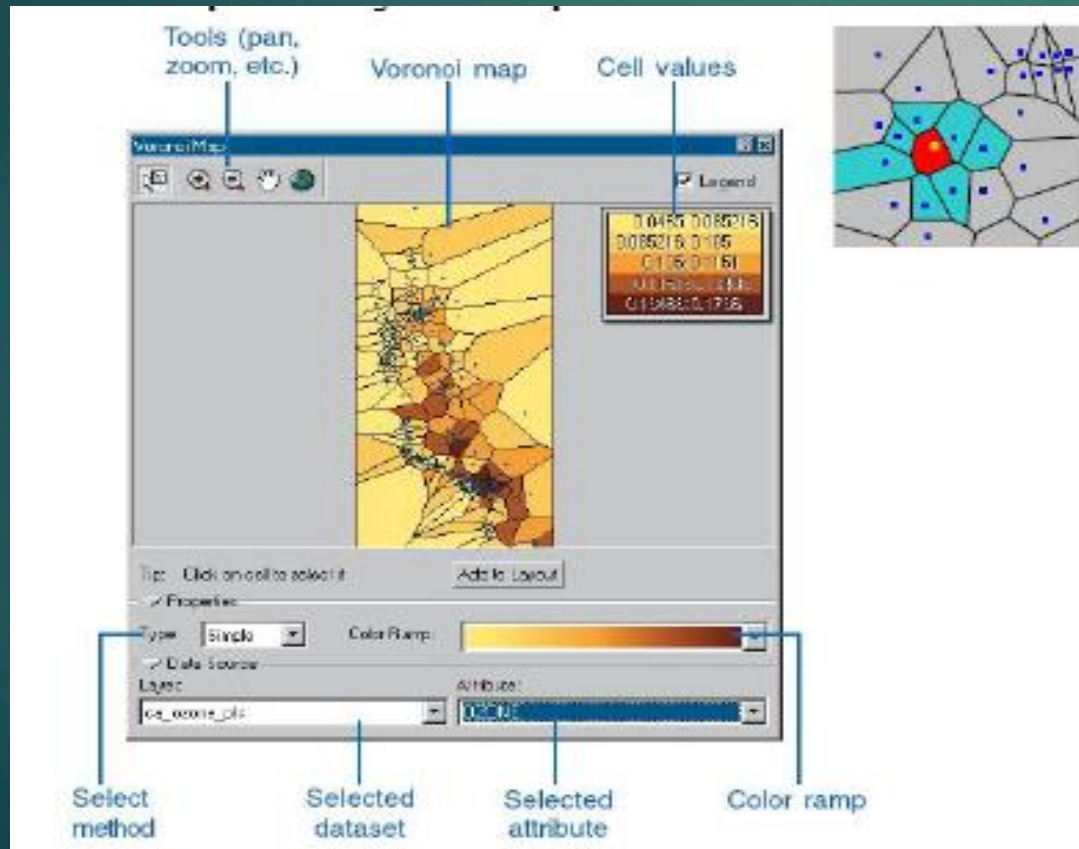
Voronoi diagram = Thiessen
polygons



Raster representation of spatial models field shapes

Voronoi diagram = Thiessen polygons

2 . Irregular division



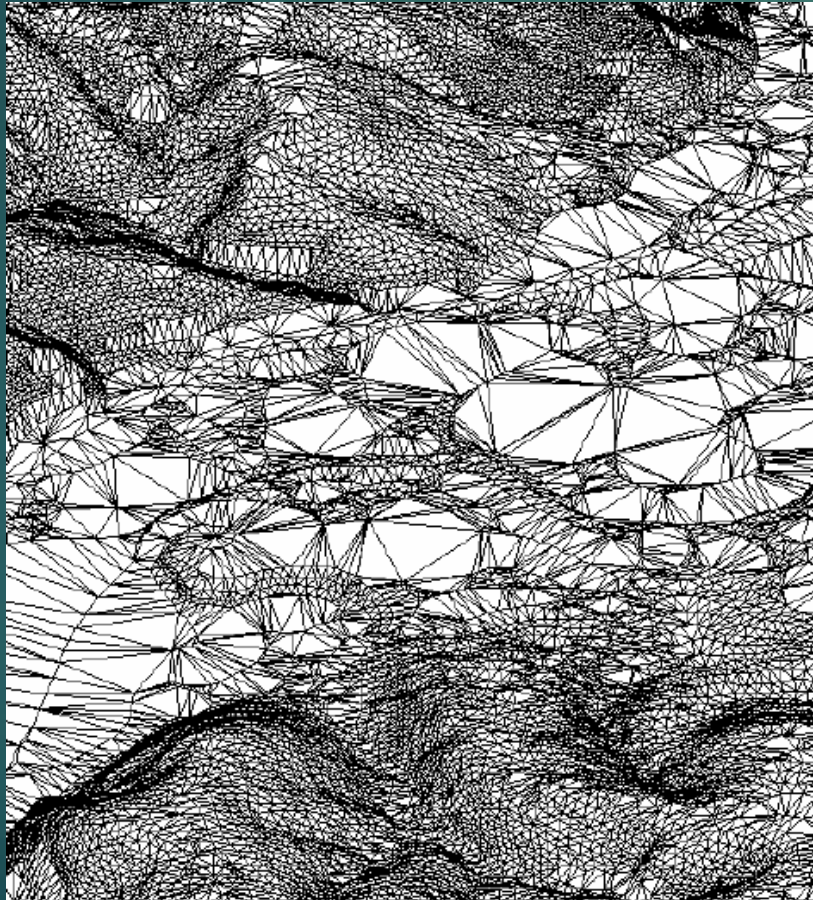
Delauney triangles – here only the vertices of the original triangles, i.e. the measured values,

the polygon area is assigned the value of this measured point

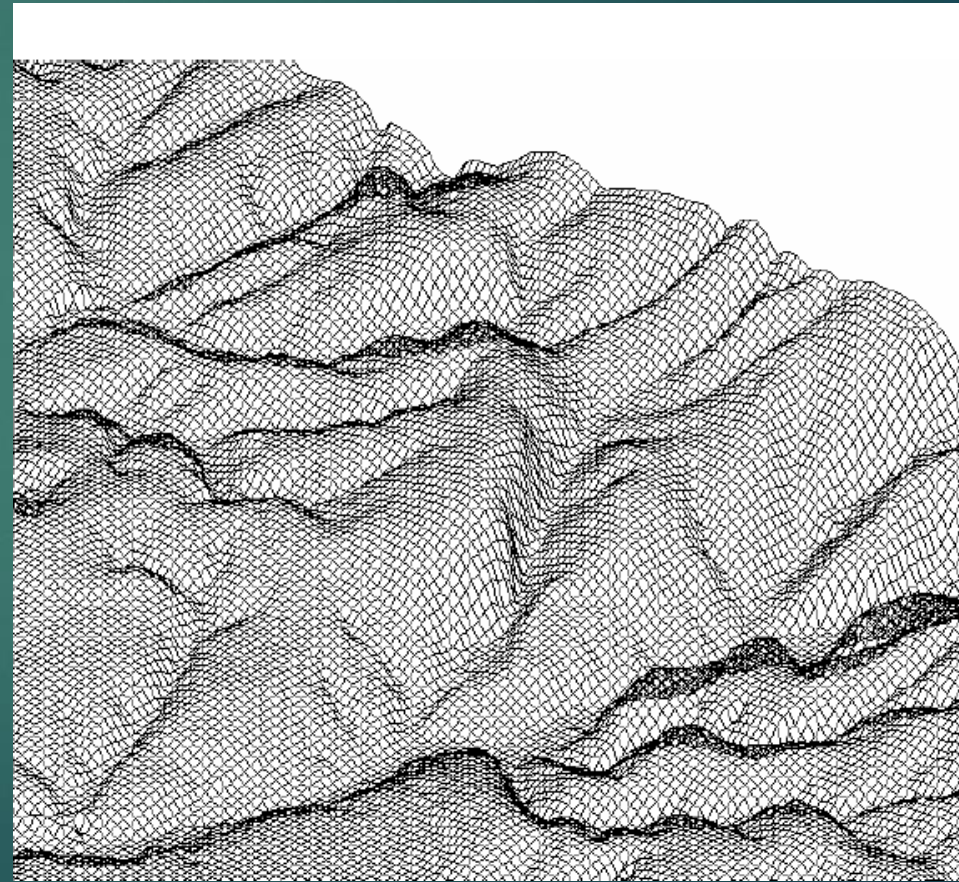
Raster representation of spatial models

field shapes

triangular network



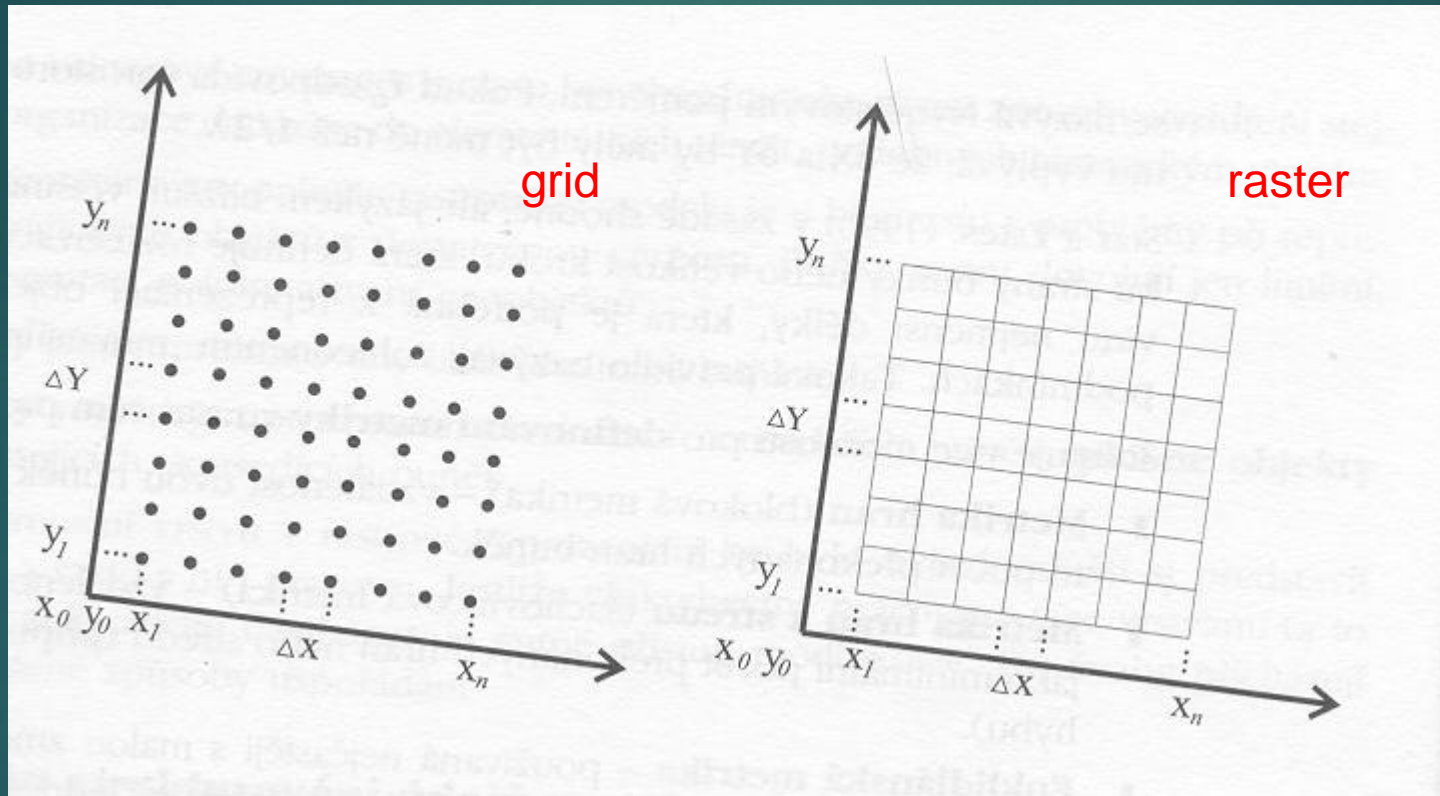
grid network - see below



Raster representation of spatial models

grid x raster

10



grid – values given in

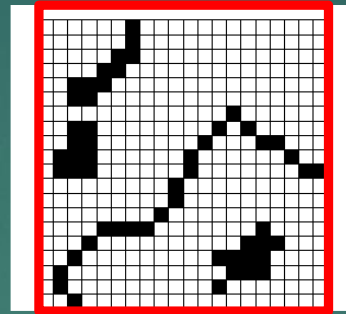
raster nodes – values in pixels, these are values for entire pixel areas, the value is stored in the center of the pixel

Raster representation of spatial models

model creation

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Modeling process - procedure:



1. definition of spatial frame F (area size and detail of division into fields = cells = pixels)
2. finding suitable domains for attribute (range of values stored in individual cells)
3. selection of phenomenon values in the spatial framework (what will be the content of the values in the cells – classes – altitudes, types of soil, ...)
4. then analyzes can already be performed using calculations with functions (what will be calculated, ...)

Raster representation of spatial models

creation of a model - creation of a spatial framework

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1 . the task is to design a field model = **creating a spatial framework**

i.e. division into a **final mosaic of planar elements** (eg pixels)

area elements = locations = locations

surface elements - sometimes replaced by points (grid)

Raster representation of spatial models

creation of a model - creation of a spatial framework

The model has a so-called finite structure

- ▶ regular = quadrilaterals, ..
 - ▶ cell raster = cell raster - DPZ data, mapping
 - ▶ dot raster = point raster – elevation chart (grid)
- ▶ irregular = triangles (e.g. from points measured on Earth)

there are mutual **conversions** between them (vector raster)

modeled phenomena expressed by **sample values, they are not continuous values, it is only a model**

Raster representation of spatial models

, creation of a model, creation of a spatial framework

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Euclidean space = plane is most often used

space model based on fields (pixels, triangles, ...) formed by a finite number n spatial fields f_i spatial frame F)

$$f_i: 1 \leq i \leq n$$

every spatial field has a computable/measurable function f_i F frame meeting values

attribute domains A_i (the domain determines the range of applicable values of the given attribute)

Raster representation of spatial models

creation of a model - creation of a spatial framework

To make the model **computable** :

- ▶ the number of fields (CELLS, PIXELS) forming the **spatial frame** must be **finite**
- ▶ function f ; in all fields must be **defined** (**unknown value = zero**),
- ▶ **domain of attributes** must be defined = a subset of **real numbers** (**integer** , **double precision** , ...) and these are then the ***z values*** (**values** of the given attribute) of the Euclidean space x, y – e.g. DMT

Raster representation of spatial models

regular grid - creating a spatial frame

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Geometrical definition of a regular grid:

1. Determining **the origin** of coordinates about $s X_0, Y_0$
2. Determining **the direction of the** coordinate axes (Y often reversed compared to math axes, origin is top left)
3. Set **the pixel size of** the raster $\Delta x, \Delta y$
4. **Raster size** - number of pixels multiplied $\Delta x \cdot \Delta y$ (valid for square pixels, where $\Delta x = \Delta y$) or the product of the differences of the minimum and maximum coordinates in both directions

Raster representation of spatial models

regular grid - creating a spatial frame

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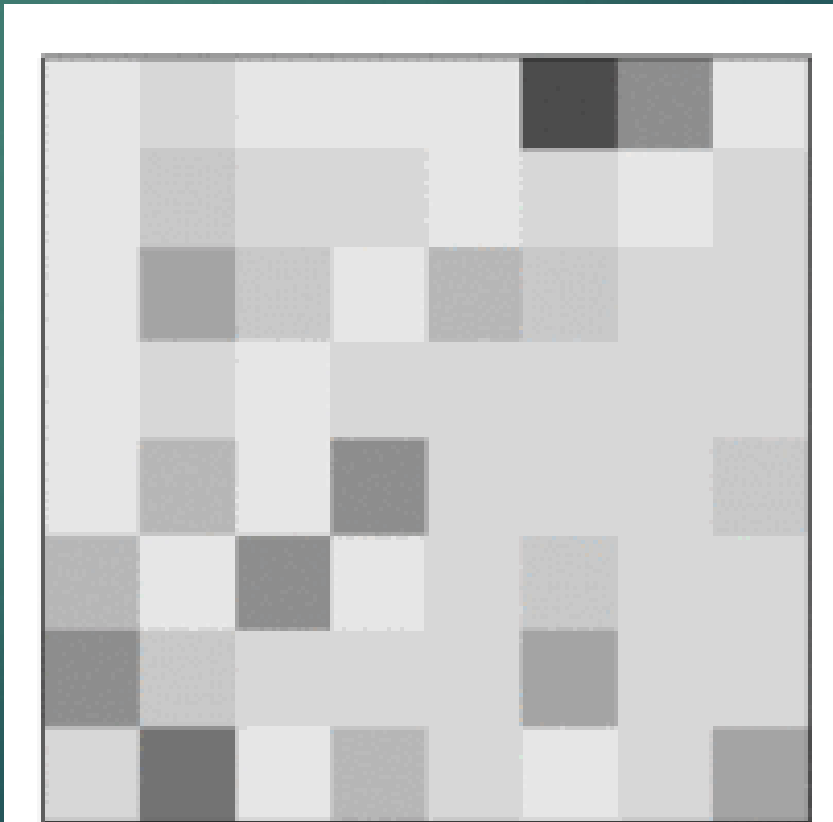
For a regular square (rectangular) representation, the spatial frame is divided into

columns (columns)

lines (rows)

- ▶ **column** has a width Δx
- ▶ **line** has a height Δy

For a square cell: $\Delta x = \Delta y$



Raster representation of spatial models

regular grid - creating a spatial frame

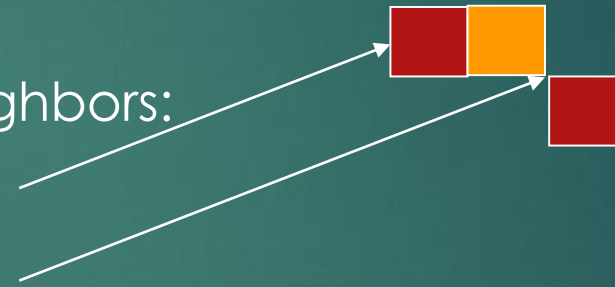
18

$\Delta x, \Delta y$ - indicates the **resolution of the raster** (**raster resolution**)

Topology - each pixel - 2 types of neighbors:

common edge - **full neighbor** (**full**)

common point - **diagonal neighbor**



square pixels - 8 neighbors - 4 solid and 4 diagonal

Raster representation of spatial models

volume of data of a regular square raster

Raster model:

total data volume given

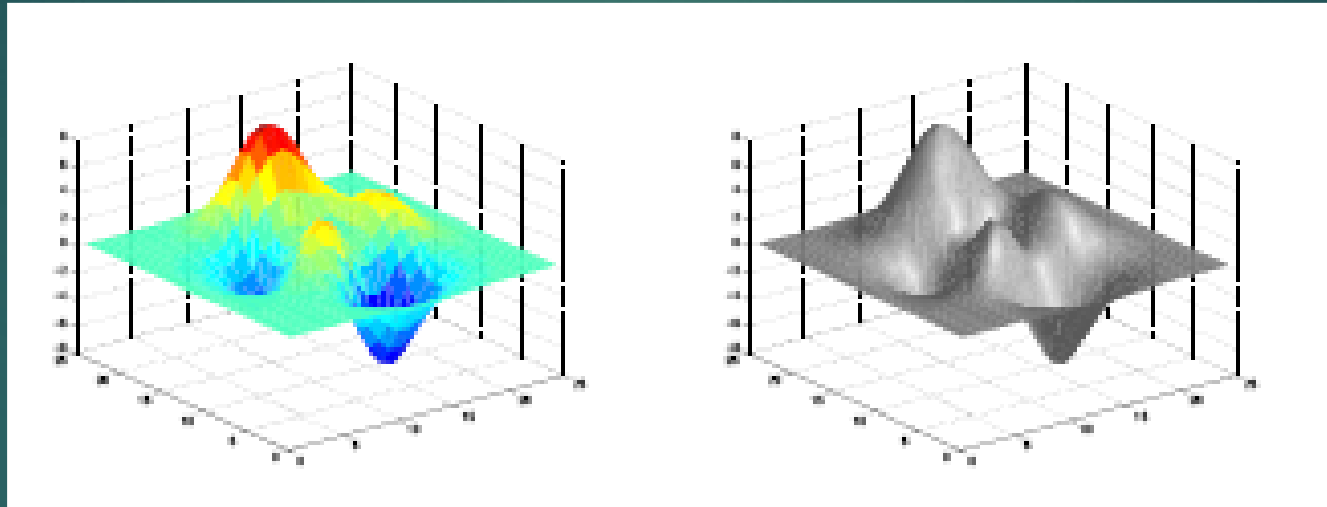
1. by the total **number of** cells/pixels
2. **multiplied by the value** , which is given by the value corresponding to the number of bits for the given layer/plane (for 1-bit data = $\frac{1}{8}$, 8-bit data = 1 , 24-bit data = 3)
3. **and multiplied by number of layers=planes**

This type of model tends to have a larger volume of data than a vector model

Raster representation of spatial models

model creation

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Raster model:

Attribute is expressed as a value that can be displayed

• **in 3D** or

• **only by color in 2D** - the color expresses the attribute value - a legend must be attached

Raster representation of spatial models value in an array

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Each field/cell/pixel of the model in one layer

contains 1 value for the given information,

if the class does not exist in a given place or is unknown , it
has a value equal to zero, it is referred to as NULL

Raster representation of spatial models

Attribute domains

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Attribute Value Types (Cells)

Values measured in different ways:

1. **nominal** – the created **field** is referred to as **categorical**

arithmetic operations cannot be performed with them,
with the exception of carefully selected values (sums of coded values)

e.g.

- ⦿ *boolean values* - yes, no,
- ⦿ *designation of land use classes with numbers* - water pixels with a value of 1, forest pixels with a value of 2 - the values can be swapped, but the information content remains)

Raster representation of spatial models

Attribute domains

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Attribute value types

Values measured in different ways:

1. **nominal** - the created field is referred to as **categorical**

arithmetic operations cannot be performed with them,
except for carefully chosen exceptions (sums of coded values)

Calculation example with nominal values: sum of coded values:

1st class values 1 – 20

2nd class values 1000, 1100, 1200, 1300,

From the sum of 1220, I know that this is the area where the 1st class with a value of 20 and the 2nd class occur, with a value of 1200

There must not be a result that has the same value, but different input values of adders

Raster representation of spatial models

Attribute domains

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2. ordinal - quantifies by including values **on a linear scale** ,

they can be compared by size but
they cannot be counted on indefinitely

- 
- ▶ *year of foundation 900 , year of foundation 1800 - the second building is not twice as old as the first*
 - ▶ *temperature in °C, temperature in °F - doubling one is not equal to doubling the other, the difference can be expressed*

Raster representation of spatial models

Attribute domains

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3. interval - quantities defined using a position on an interval scale without specifying a fixed point

certainly arithmetic operations are **possible**

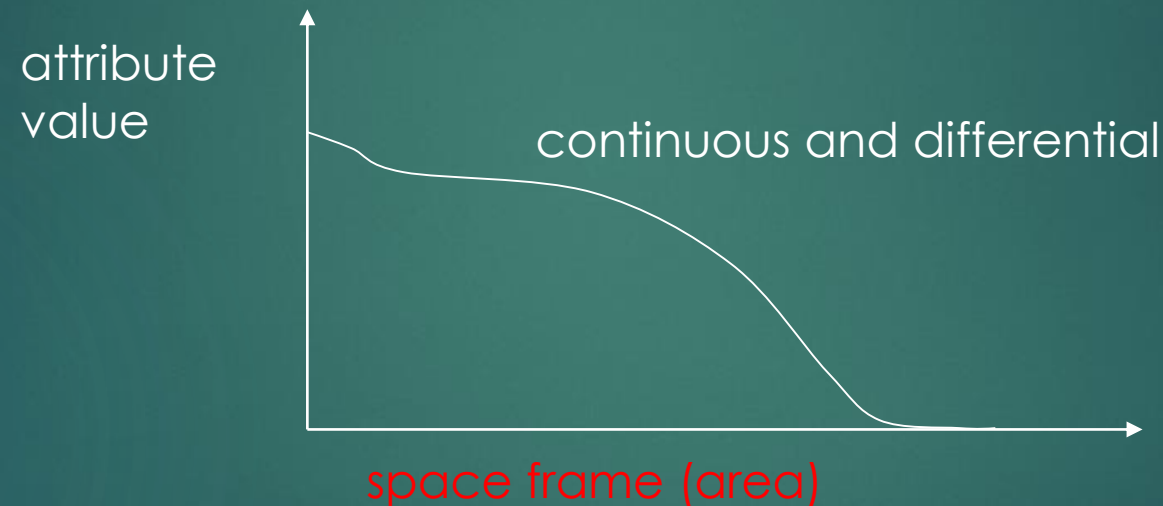
0 – 200 mm/year of rainfall, 201 – 400 mm/year of rainfall ...

4. proportional - measurement on a proportional scale for a given zero point,

arithmetic operations are **possible**

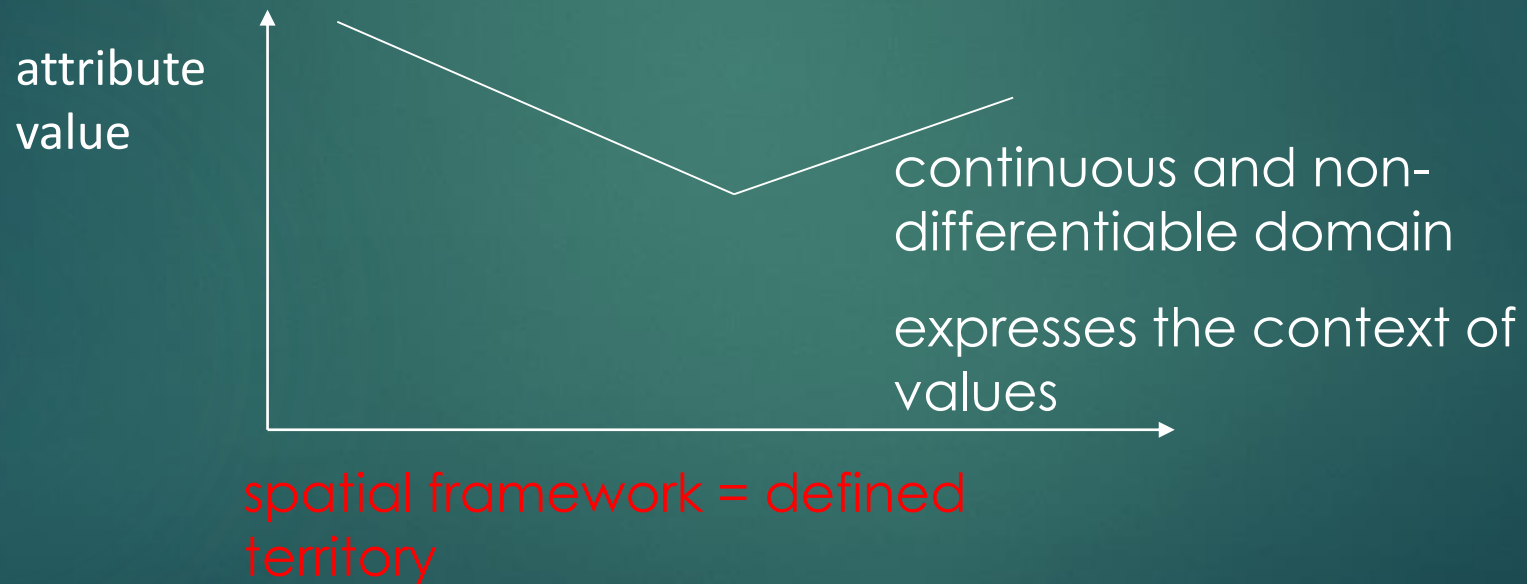
age, frequency, speed, length of time

1. continuous attribute values differential = continuous **small** changes in position cause small changes in attribute values



differential field - if the function describing the attribute is **differential** and has a defined **slope** (the function is monotonic)

2. Continuous and non-differentiable fields = attribute values



3. discontinuous and non-differential field = attribute values



Raster representation of spatial models

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Spatial change can be:

- ▶ **fluent** - (e.g. movement in space) - **can be interpolated** between states
- ▶ **sudden** - **cannot be interpolated**



Raster representation of spatial models

Attribute domains

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Types of fields according to behavior in space

1. Field **isotropic** - properties independent of direction
2. **Anisotropic** field - direction dependent properties -
(more common in the real world)

Raster representation of spatial models

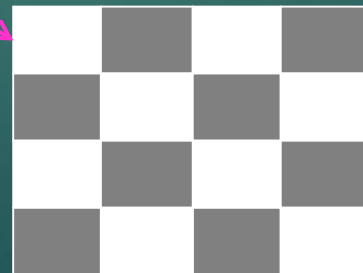
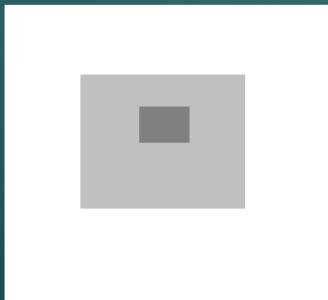
Attribute domains

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Relationships between adjacent field values

spatial autocorrelation - "everything is related to everything else, but closer things more so" - measures the degree of clustering

1. **positive autocorrelation** - tendency to cluster similar values
2. **negative autocorrelation** - similar values are distant from each other



Raster representation of spatial models

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Definition of the topic

Definition of the **theme** of raster layers (=what values are in the raster fields)

1. *object* approach

- e.g. topographic map – built-up area, field, forest – separate classes in one raster – corresponding areas of the classes are displayed in one color, i.e. they contain pixels with the same value

2. *layered* access

- one raster represents one class with different values - eg a map of average temperatures - different values in pixels represent different average temperatures of an area

They can be combined